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Extreme values for Benedicks–Carleson quadratic maps

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Abstract. We consider the quadratic family of maps given by $f_a(x) = 1 - ax^2$ with $x \in [-1, 1]$, where a is a Benedicks–Carleson parameter. For each of these chaotic dynamical systems we study the extreme value distribution of the stationary stochastic processes $X_0, X_1, \ldots$, given by $X_n = f_a^n$, for every integer $n \geq 0$, where each random variable X_n is distributed according to the unique absolutely continuous, invariant probability of f_a. Using techniques developed by Benedicks and Carleson, we show that the limiting distribution of $M_n = \max\{X_0, \ldots, X_{n-1}\}$ is the same as that which would apply if the sequence $X_0, X_1, \ldots$ was independent and identically distributed. This result allows us to conclude that the asymptotic distribution of M_n is of type III (Weibull).

1. *Introduction*

The dynamical systems we consider in this work are the quadratic maps given by $f_a(x) = 1 - ax^2$ on $I = [-1, 1]$, with $a \in \mathcal{BC}$, where $\mathcal{BC}$ is the Benedicks–Carleson parameter set introduced in [**BC85**]. The set $\mathcal{BC}$ has positive Lebesgue measure and is built in such a way that, for every $a \in \mathcal{BC}$, the Collet–Eckmann condition holds: there is exponential growth of the derivative of f_a along the critical orbit, i.e. there exists $c > 0$ such that

$$|(f_a^n)'(f_a(0))| \geq e^{cn},$$

for all $n \in \mathbb{N}$. This property guarantees not only the non-existence of an attracting periodic orbit but also the existence of an ergodic f_a-invariant probability measure μ_a that is absolutely continuous with respect to Lebesgue measure on $[-1, 1]$. In fact, these Benedicks–Carleson systems are chaotic and highly sensitive to initial conditions. Actually, after some iterates, the behavior of most orbits becomes erratic and distributed on

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the set $[-1, 1]$ according to the invariant measure μ_a. Hence, it is meaningful to study the statistical properties of the orbits of these systems and, here, we are particularly concerned with their extreme type behavior.

A natural way to build a stationary stochastic process associated to f_a, for some $a \in \mathcal{BC}$, is to consider the random variable (r.v.) X_0 defined on the probability space $([-1, 1], \mu_a)$, taking values on $[-1, 1]$ with distribution function (d.f.) $G_a(x) = \mu_a\{(-\infty, x] \cap [-1, 1]\}$ and then iterate it by f_a, i.e. define

$$X_n = f_a(X_{n-1}) = f_a^n(X_0) \quad \text{for each } n \in \mathbb{N}. \tag{1.1}$$

This way, we obtain a stationary stochastic process $X_0, X_1, X_2, \ldots$ with common marginal d.f. given by $G_a(x) = \mu_a\{X_0 \le x\}$. The stationarity results from the f_a-invariance of the probability measure μ_a (see for example [**KT66**, §15.4]). Our goal is to study the asymptotic distribution of the partial maximum

$$M_n = \max\{X_0, X_1, \ldots, X_{n-1}\}, \tag{1.2}$$

when properly normalized.

The study of distributional properties of the higher order statistics of a sample, like the maximum of the sample, is the purpose of extreme value theory. Its major classical theorem asserts that there are only three types of non-degenerate asymptotic distributions for the maximum of an independent and identically distributed (i.i.d.) sample under linear normalization.

The main result of this work states that the limiting law of M_n is the same as if $X_0, X_1, \ldots$ were independent with the same d.f. G_a. In fact, we verify that under appropriate normalization the asymptotic distribution of M_n is of type III (Weibull). As usual, we denote by G_a^{-1} the generalized inverse of the d.f. G_a, which is to say that $G_a^{-1}(y) := \inf\{x : G_a(x) \ge y\}$.

THEOREM A. *For each $a \in \mathcal{BC}$ and every stationary stochastic process $(X_i)_{i\in\mathbb{N}_0}$ given by (1.1), we have*

$$P\{a_n(M_n - 1) \le x\} \to H(x) = \begin{cases} e^{-(-x)^{1/2}}, & x \le 0, \\ 1, & x > 0, \end{cases}$$

where $a_n = (1 - G_a^{-1}(1 - 1/n))^{-1}$.

Haiman [**Hai03**] has obtained a similar asymptotic result for the natural stochastic process associated with the tent map. The arguments used here for quadratic maps would allow us to obtain a different proof of Haiman's theorem.

Also, a study concerning extremes for dynamical systems, essentially focusing on the finite sample behavior of maxima, has already been done by Balakrishnan *et al* in [**BNN95**].

More recently, Collet [**Co01**] has studied the asymptotic distribution of the partial maximum of the stochastic process $Y_1, Y_2, \ldots$ given by $Y_n = -\log|\xi - f^n|$, where ξ is a reference point in the phase space and f a C^2 non-uniformly hyperbolic interval map. He obtained that the Gumbel's limiting law applies for Lebesgue-almost every point ξ chosen in the phase space. However, the critical point and its orbit are not included in this full Lebesgue measure set of points.

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2. *Motivation and strategy*

The study of the limit behavior for maxima of a stationary process can be reduced, under adequate conditions on the dependence structure, to the classical extreme value theory for sequences of i.i.d. random variables. Hence, to the stationary process $X_0, X_1, \ldots$ we associate an independent sequence of r.v.s denoted by $Z_0, Z_1, \ldots$ with common d.f. given by $G_a(x) = P\{X_0 \le x\} = \mu_a\{X_0 \le x\}$. We also set, for each $n \in \mathbb{N}$,

$$\hat{M}_n = \max\{Z_0, \ldots, Z_{n-1}\}. \tag{2.1}$$

Let us focus on the conditions that allow us to relate the asymptotic distribution of M_n with that of $\hat{M}_n$. Following [**LLR83**] we refer to these conditions as $D(u_n)$ and $D'(u_n)$, where u_n is a suitable sequence of thresholds converging to $\max_{z\in[-1,1]} X_0(z) = 1$, as n goes to ∞, that will be defined below. $D(u_n)$ imposes a certain type of distributional mixing property. Essentially, it says that the dependence between some special types of events fades away as they become more and more apart in the time line. $D'(u_n)$ restricts the appearance of clusters, that is, it makes the occurrence of consecutive 'exceedances' of the level u_n an unlikely event.

Consider a sequence of stationary r.v.s $Y_1, Y_2, \ldots$ with common d.f. F. We say that an *exceedance* of the *level* u_n occurs at time i if $Y_i > u_n$. The probability of such an exceedance is $1 - F(u_n)$ and so the mean value of the number of exceedances occurring up to n is $n(1 - F(u_n))$. The sequences of levels u_n we consider are such that $n(1 - F(u_n)) \to \tau$ as $n \to \infty$, for some $\tau \ge 0$, which means that, in a time period of length n, the expected number of exceedances is approximately τ.

Observe that, in the case of our stationary process $X_0, X_1, \ldots$, we have $X_j > u_n$ if and only if $|X_{j-1}| < \sqrt{(1-u_n)/a}$. Since $u_n \to 1$ as $n \to \infty$, then, for large n, an exceedance of the level u_n is always preceded by a return to within a tight vicinity of the critical point. Hence, as one would expect, there is an intimate relation between exceedances and deep returns to the vicinity of the critical point.

$D(u_n)$ is a type of mixing requirement specially adapted to extreme value theory. In this context, the events of interest are those of the form $\{X_i \le u\}$ and their intersections. Observe that $\{M_n \le u\}$ is just $\{X_0 \le u, \ldots, X_{n-1} \le u\}$. A natural mixing condition in this context is the following. Let $G_{i_1,\ldots,i_n}(x_1, \ldots, x_n)$ denote the joint d.f. of $X_{i_1}, \ldots, X_{i_n}$ and set $G_{i_1,\ldots,i_n}(u) = G_{i_1,\ldots,i_n}(u, \ldots, u)$.

Condition ($D(u_n)$). We say that $D(u_n)$ holds for the sequence $X_0, X_1, X_2, \ldots$ if, for any integers $i_1 < \cdots < i_p$ and $j_1 < \cdots < j_k$ for which $j_1 - i_p > m$, and any large $n \in \mathbb{N}$,

$$|G_{i_1,\ldots,i_p,j_1,\ldots,j_k}(u_n) - G_{i_1,\ldots,i_p}(u_n)G_{j_1,\ldots,j_k}(u_n)| \le \gamma(m),$$

where $\gamma(m) \to 0$ as $m \to \infty$.

We remark that the actual definition of $D(u_n)$ appearing in [**LLR83**, §3.2] is a weaker requirement. Following [**Co01**], we proposed, very recently, in [**FF07**], a reformulation of condition $D(u_n)$ that follows almost immediately from the decay of correlations of the system and together with $D'(u_n)$ still allows us to relate the asymptotic distributions of M_n and $\hat{M}_n$.

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Condition ($D'(u_n)$). We say that $D'(u_n)$ holds for the sequence $X_0, X_1, X_2, \ldots$ if

$$\lim_{k\to\infty} \limsup_{n\to\infty} n \sum_{j=1}^{[n/k]} P\{X_0 > u_n \text{ and } X_j > u_n\} = 0. \tag{2.2}$$

The sequence u_n is such that the average number of exceedances in the time interval $\{0, \ldots, [n/k]\}$ is approximately τ/k, which goes to zero as $k \to \infty$. However, the exceedances may have a tendency to be concentrated in the time period following the first exceedance at time zero. Condition 2.2 prevents this from happening, i.e. it forbids the concentration of exceedances by bounding the probability of more than one exceedance in the time interval $\{0, \ldots, [n/k]\}$. This guarantees that the exceedances should appear scattered through the time period $\{0, \ldots, n-1\}$.

The special relevance of both these conditions is connected to Theorem 3.5.2 of [**LLR83**]: let a_n and b_n be sequences such that $P\{a_n(\hat{M}_n - b_n) \le x\} \to H(x)$ for some non-degenerate d.f. H; if $D(u_n)$, $D'(u_n)$ hold for the stationary sequence $X_1, X_2, \ldots$, when $u_n = x/a_n + b_n$ for each x, then $P\{a_n(M_n - b_n) \le x\} \to H(x)$. This means that if we are able to show that conditions $D(u_n)$ and $D'(u_n)$ are valid for the stationary process $X_0, X_1, \ldots$, then M_n and $\hat{M}_n$ share the same asymptotic distribution with the same normalizing sequences. Consequently, our strategy to prove Theorem A is the following.

- Compute the limiting distribution of $\hat{M}_n$ and the associated normalizing sequences a_n and b_n.
- Show that conditions $D(u_n)$ and $D'(u_n)$ are valid for the stochastic process $X_0, X_1, X_2, \ldots$ defined in (1.1).

The rest of the paper is dedicated to the proof of these assertions and is structured as follows. In §3, we describe the properties of the dynamical systems f_a, with $a \in \mathcal{BC}$, and the Benedicks–Carleson techniques. The validity of condition $D(u_n)$ is a consequence of the very good mixing properties of the systems considered here. Actually, it follows from the fact that these systems possess a weak-Bernoulli generator (see §3.8 and Remark 3.1). Then, in §4, we study the asymptotic behavior of the maximum in the i.i.d. case, and identify the limiting distribution of $\hat{M}_n$ and the respective normalizing sequences a_n and b_n. Hence, we are left with the burden of proving $D'(u_n)$. In §5, we use the geometric properties of the systems to show Proposition 5.2 that paves the way for the proof of $D'(u_n)$ which is finally established in §6. In §7, we present a small simulation study in order to compare the finite sample behavior of the normalized M_n with the asymptotic one.

3. *Properties of the Benedicks–Carleson parameters*

The Benedicks–Carleson theorem (see [**BC85**] or §2 of [**BC91**]) states that there exists a positive Lebesgue measure set of parameters, $\mathcal{BC}$, verifying the following statements:

$$\text{there exists } c > 0 \ (c \approx \log 2) \text{ such that } |Df_a^n(f_a(0))| \ge e^{cn} \text{ for all } n \ge 0; \tag{EG}$$

$$\text{there is a small } \alpha > 0 \text{ such that } |f_a^n(0)| \ge e^{-\alpha\sqrt{n}} \text{ for all } n \ge 1. \tag{BA}$$

Before we describe the Benedicks–Carleson strategy let us have an overview of its key ingredients. The *critical region* is the interval $(-\delta, \delta)$, where $\delta = e^{-\Delta} > 0$ is chosen small

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but much larger than $2 - a$. This region is partitioned into the intervals

$$(-\delta, \delta) = \bigcup_{m \geq \Delta} I_m,$$

where $I_m = (e^{-(m+1)}, e^{-m}]$ for $m > 0$ and $I_m = -I_{-m}$ for $m < 0$; then each I_m is further subdivided into m^2 intervals $\{I_{m,j}\}$ of equal length inducing the partition $\mathcal{P}_0$ of $[-1, 1]$ into

$$[-1, -\delta) \cup \bigcup_{m,j} I_{m,j} \cup (\delta, 1]. \tag{3.1}$$

Given $J \in \mathcal{P}$, let nJ denote the interval n times the length of J centered at J and define $U_m := (-e^{-m}, e^{-m})$, for every $m \in \mathbb{N}$. In order to study the growth of $Df_a^n(x)$, for $x \in [-1, 1]$ and $a \in \mathcal{BC}$, the orbit is split into free periods and bound periods. During the former we are certain that the orbit never visits the critical region. The latter begin when the orbit returns to the critical region and initiates a bound to the critical point, accompanying its early iterates. The behavior of the derivative during these periods is detailed in §§3.1 and 3.2.

3.1. *Expansion outside the critical region.* There exist $c_0 > 0$ and $M_0 \in \mathbb{N}$ such that:

(1) if $x, \ldots, f_a^{k-1}(x) \notin (-\delta, \delta)$ and $k \geq M_0$, then $|Df_a^k(x)| \geq e^{c_0 k}$;
(2) if $x, \ldots, f_a^{k-1}(x) \notin (-\delta, \delta)$ and $f_a^k(x) \in (-\delta, \delta)$, then $|Df_a^k(x)| \geq e^{c_0 k}$;
(3) if $x, \ldots, f_a^{k-1}(x) \notin (-\delta, \delta)$, then $|Df_a^k(x)| \geq \delta e^{c_0 k}$.

If we were capable of keeping the orbit of x away from the critical region then it would be in the *free period* forever and the estimates above would apply. However, it is inevitable that almost every $x \in [-1, 1]$ makes a *return* to the critical region. We say that $n \in \mathbb{N}$ is a *return time* of the orbit of x if $f_a^n(x) \in (-\delta, \delta)$. Every free period of x ends with a *free return* to the critical region. We say that the return had a *depth* of $m \in \mathbb{N}$ if $f_a^n(x) \in I_{\pm m}$, which is equivalent to saying that $m = \big[-\log |f_a^n(x)|\big]$. Once in the critical region, the orbit of x initiates a binding with the critical point.

3.2. *Bound period definition and properties.* Let $\beta = 14\alpha$. For $x \in (-\delta, \delta)$ define $p(x)$ to be the largest integer p such that

$$|f_a^k(x) - f_a^k(0)| < e^{-\beta k} \quad \text{for all } k < p. \tag{3.2}$$

Then

(1) $\frac{1}{2}|m| \leq p(x) \leq 3|m|$, for each $x \in I_m$;
(2) $|Df_a^p(x)| \geq e^{c' p}$, where $c' = (1 - 4\beta)/3 > 0$.

The orbit of x is said to be bound to the critical point during the period $0 \leq k < p$. We may assume that p is constant on each $I_{m,j}$. Note that during the bound period the orbit of x may return to the critical region. These instants are called *bound return times*.

Roughly speaking, the idea behind the proof of the Benedicks–Carleson theorem is that while the orbit of the critical point is outside the critical region we have expansion (see §3.1); when it returns we have a serious setback in the expansion but then, by continuity, the orbit repeats its early history regaining expansion on account of (EG).

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To arrange for the exponential growth of the derivative along the critical orbit (EG) one has to guarantee that the losses at the returns are not too drastic; hence, by parameter elimination, the basic assumption condition (BA) is imposed. The argument is mounted in a very intricate induction scheme that guarantees both the conditions for the parameters that survive the exclusions. The condition (EG) is usually known as the Collet–Eckmann condition and it was introduced in [**CE83**].

3.3. *Bookkeeping, essential and inessential returns.* A sequence of partitions $\mathcal{P}_0 \prec \mathcal{P}_1 \prec \cdots$ is built so that points in the same element of the partition $\mathcal{P}_n$ have the same history up to time n. For a detailed description of the construction of this sequence of partitions in the phase space setting we refer to [**Fre05**, §4]. Here, we highlight some of the main aspects of its construction.

For Lebesgue almost every $x \in I$, $\{x\} = \bigcap_{n\geq 0} \omega_n(x)$, where $\omega_n(x)$ is the element of $\mathcal{P}_n$ containing x. For such x there is a sequence $t_1, t_2, \ldots$ corresponding to the instants when the orbit of x experiences a free *essential return situation*, which means $I_{m,k} \subset f_a^{t_i}(\omega_{t_i-1}(x))$ for some $|m| \geq \Delta$ and $1 \leq k \leq m^2$. We have that $\omega_n(x) = \omega_{t_{i-1}}(x)$, for every $t_{i-1} \leq n < t_i$ and $f_a^{t_i}(\omega_{t_i}(x)) = \omega_0(f^{t_i}(x))$, except for the points at the two ends of $f_a^{t_i}(\omega_{t_{i-1}}(x))$ for which it may occur an adjoining to the neighboring interval. If t_i is an essential return situation for x, then it is either an *essential return time* for x, which means that there exists $m \geq \Delta$ and $1 \leq k \leq m^2$ such that $I_{m,k} \subset f_a^{t_i}(\omega_{t_i}(x)) \subset 3I_{m,k}$; or an *escaping time* for x, which is to say that $I_{(\Delta-1),1} \subset f_a^{t_i}(\omega_{t_i}(x)) \subset (\delta, 1]$ or $I_{-(\Delta-1),1} \subset f_a^{t_i}(\omega_{t_i}(x)) \subset [-1, -\delta)$, where $I_{\pm(\Delta-1),1}$ is the subinterval of $I_{\pm(\Delta-1)}$ closest to zero.

We remark that every point in $\omega \in \mathcal{P}_n$ has the same history up to n, in the sense that they have the same free periods, return to the critical region simultaneously, with the same depth and their bound periods expire at the same time.

We say that v is a free return time for x of *inessential* type if $f_a^v(\omega_v(x)) \subset 3I_{m,k}$, for some $|m| \geq \Delta$ and $1 \leq k \leq m^2$, but $f_a^v(\omega_v(x))$ is not large enough to contain an interval $I_{m,k}$ for some $|m| \geq \Delta$ and $1 \leq k \leq m^2$.

3.4. *Distortion of the derivative.* The sequence of partitions described above is designed so that we have bounded distortion in each element of the partition $\mathcal{P}_{n-1}$ up to time n. To be more precise, consider $\omega \in \mathcal{P}_{n-1}$. There exists a constant C independent of ω, n and the parameter a such that, for every $x, y \in \omega$,

$$\frac{|Df_a^n(x)|}{|Df_a^n(y)|} \leq C. \tag{3.3}$$

See [**Fre05**, Lemma 4.2] for a proof.

3.5. *Growth of returning and escaping components.* Let t be an essential return time for $\omega \in \mathcal{P}_t$, with $I_{m,k} \subset f_a^t(\omega) \subset 3I_{m,k}$ for some $m \geq \Delta$ and $1 \leq k \leq m^2$. If n is the next free return situation for ω (either essential or inessential) then

$$|f_a^n(\omega)| \geq e^{c_0 q} e^{-5\beta|m|}, \tag{3.4}$$

where $q = n - (t + p)$. See [**Fre05**, Lemma 4.1].

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Suppose that $\omega \in \mathcal{P}_t$ is an escape component. Then, in the next return situation for ω, at time t_1, we have that

$$|f_a^{t_1}(\omega)| \geq e^{-\beta\Delta}. \tag{3.5}$$

See [**MS93**], [**Fre06**, Lemma 4.2] or [**Mor93**, Lemma 5.1] for a proof of a similar statement in the space of parameters.

3.6. *Existence of absolutely continuous invariant measures.* For every $a \in \mathcal{BC}$, the quadratic map f_a has an invariant probability measure μ_a that is absolutely continuous with respect to Lebesgue measure on $[-1, 1]$. The existence of absolutely continuous invariant measures (a.c.i.m.) for a positive Lebesgue measure set of parameters was first proved by Jakobson in [**Jak81**] and others followed (see for example [**CE83, BC85, Now85, Ryc88, BY92**] and [**You92**]).

The a.c.i.m. $\mu_a = \rho_a\, dx$ has the following properties:

(1) μ_a is the only a.c.i.m. of f_a;

(2) (f_a, μ_a) is exact;

(3) $\rho_a = \rho_1^a + \rho_2^a$, where ρ_1^a has bounded variation and

$$0 \leq \rho_2^a(x) \leq \text{const} \sum_{j=1}^{\infty} \frac{(1.9)^{-j}}{\sqrt{|x - f_a^j(0)|}};$$

(4) the support of μ_a is $[f_a^2(0),\ f_a(0)]$ and $\inf_{x\in[f_a^2(0),\, f_a(0)]} \rho_a(x) > 0$.

The proof of these statements can be found in [**You92**, Theorems 1 and 2].

3.7. *Decay of correlations and the central limit theorem.* The Benedicks–Carleson quadratic maps have good statistical behavior. In fact, Young proved that these maps have exponential decay of correlations and satisfy the central limit theorem [**You92**, Theorems 3 and 4]. This was also obtained by Keller and Nowicki in [**KN92**]. To be more precise, for every $a \in \mathcal{BC}$, there exists $\varsigma \in (0, 1)$ such that for all $\varphi, \psi : [-1, 1] \to \mathbb{R}$ with bounded variation, there exists $C = C(\varphi, \psi)$ such that

$$\left| \int \varphi \cdot (\psi \circ f_a^n)\, d\mu_a - \int \varphi\, d\mu_a \int \psi\, d\mu_a \right| \leq C\varsigma^n \quad \text{for all } n \geq 0. \tag{3.6}$$

Moreover, if $\int \varphi\, d\mu_a = 0$ then for every $x \in \mathbb{R}$ we have

$$\mu_a\left\{ \frac{1}{\sqrt{n}} \sum_{i=0}^{n-1} \varphi \circ f_a^i \leq x \right\} \xrightarrow[n\to\infty]{} \Phi(x/\sigma), \tag{3.7}$$

where we are assuming that

$$\sigma := \lim_{n\to\infty} \frac{1}{\sqrt{n}} \left[\int \left(\sum_{i=0}^{n-1} \varphi \circ f_a^i \right)^2 d\mu_a \right]^{1/2} > 0$$

and $\Phi(\cdot)$ denotes the $N(0, 1)$ d.f.

3.8. *Exponential weak-Bernoulli mixing.* Keller [**Kel94**] has obtained a result even sharper than (3.6). Consider the partition of $[-1, 1]$ given by $\mathcal{Q} = \{[-1, 0), [0, 1]\}$. Also,

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for integers $k < l$, denote by $\mathcal{Q}_k^l$ the join of partitions $\bigvee_{i=k}^{l} f_a^{-i}\mathcal{Q}$ and by $\mathcal{F}_k^l$ the σ-algebra generated by $\mathcal{Q}_k^l$. According to [**Kel94**] the partition $\mathcal{Q}$ is a weak-Bernoulli generator for every f_a with $a \in \mathcal{B}C$. This means that the σ-algebra $\mathcal{F}_0^\infty$ coincides, up to sets of Lebesgue measure 0, with the Borel σ-algebra of sets in $[-1, 1]$ and that

$$\beta_m(f_a, \mathcal{Q}, \mu_a) \to 0 \quad \text{as } m \to \infty,$$

where

$$\begin{aligned}\beta_m(f_a, \mathcal{Q}, \mu_a) &:= 2 \sup_{k>0} \int \sup\{|\mu_a(A|\mathcal{F}_0^k) - \mu_a(A)| : A \in \mathcal{F}_{k+m}^\infty\}\, d\mu_a \\ &= \sup_{k\geq 1, L\geq 1} \sum_{A\in\mathcal{Q}_0^k, B\in\mathcal{Q}_{k+m}^{k+m+L}} |\mu_a(A \cap B) - \mu_a(A)\mu_a(B)|.\end{aligned}$$

In fact, [**Kel94**, Theorem 1] states that there are constants $C > 0$ and $0 < r < 1$ such that

$$\beta_m(f_a, \mathcal{Q}, \mu_a) \leq Cr^m \tag{3.8}$$

for all $m \in \mathbb{N}$.

Remark 3.1. We observe that if we refine the partition $\mathcal{Q}$ by adding one point so that $\{X_0 > u\} \in \mathcal{F}_0$, where $\mathcal{F}_0$ is the σ-algebra generated by $\mathcal{Q}$, then Keller's argument still holds with the same type of estimate as in (3.8). As a consequence, condition $D(u_n)$ is true for every considered sequence u_n.

4. *Domain of attraction of the associated i.i.d. process*

We recall that to every stationary stochastic process $X_0, X_1, X_2, \ldots$ defined in (1.1) we associated an i.i.d. sequence of r.v.s $Z_0, Z_1, Z_2, \ldots$ with common d.f. given by $G_a(x) = P\{X_0 \leq x\} = \mu_a\{(-\infty, x] \cap [-1, 1]\}$ (see §2). In this section we will determine the domain of attraction corresponding to the d.f. G_a, i.e. we will compute the limiting distribution of $\hat{M}_n$, defined in (2.1), when properly normalized. For that purpose one must look at the tail behavior of $1 - G_a(x)$ as x gets closer to $\sup_{y\in\mathbb{R}}\{G_a(y) < 1\} = 1$. According to §3.6 (3), if z is close to 1 we may write $\mu_a\{(z, 1]\} \asymp \sqrt{1-z}$, in the sense that $\mu_a\{(z, 1]\}/\sqrt{1-z} \to c$ for some $c > 0$, as $z \to 1$. Hence, for $s > 0$ sufficiently close to 0 we have

$$1 - G_a(1 - s) \asymp \sqrt{1 - (1 - s)} = \sqrt{s}, \tag{4.1}$$

which means that $\lim_{s\to 0^+}(1 - G_a(1 - s))/\sqrt{s} > 0$. At this point, we apply [**LLR83**, Theorem 1.6.2] to obtain that G_a, in this case, belongs to the domain of attraction of type III (Weibull) with parameter $1/2$, since, for every $x > 0$,

$$\lim_{h\to 0^+} \frac{1 - G_a(1 - xh)}{1 - G_a(1 - h)} = \lim_{h\to 0^+} \frac{\sqrt{xh}}{\sqrt{h}} = x^{1/2}.$$

Moreover, according to [**LLR83**, Corollary 1.6.3], if we consider the sequences defined for each $n \in \mathbb{N}$ by $b_n = 1$ and $a_n = (1 - G_a^{-1}(1 - 1/n))^{-1}$, where $G_a^{-1}(y) = \inf\{x : G_a(x) \geq y\}$, then

$$P\{a_n(\hat{M}_n - b_n) \leq x\} \to H(x) = \begin{cases} e^{-(-x)^{1/2}}, & x \leq 0, \\ 1, & x > 0, \end{cases}$$

as $n \to \infty$.

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5. *Probability of an essential return reaching a certain depth*

In the study of extremes, one is mostly interested in the probability of occurrence of exceedances of the level u_n. As we have already mentioned in §2, these events are related with the occurrence of deep returns. Thus, in this section we do some preparatory work by estimating the probability of the returns hitting a given depth.

For each $x \in I$, let $v_n(x)$ denote the number of essential return situations of x between 1 and n, let $s_n(x)$ be the number of those which are actual essential return times and let $\mathfrak{S}_n$ the number of the latter that correspond to *deep essential returns* of the orbit of x, i.e. with return depths above a threshold $\Theta \geq \Delta$. Observe that $v_n(x) - s_n(x)$ is the exact number of escaping situations of the orbit of x, up to n.

Given the integers $0 \leq s \leq 2n/\Theta$, $s \leq v \leq n$ and the s integers $\gamma_1, \ldots, \gamma_s$, each greater than or equal to Θ, we define the event

$$A^{v,s}_{\gamma_1,\ldots,\gamma_s}(n) = \{x \in I : v_n(x) = v,\ \mathfrak{S}_n(x) = s \text{ and the depth of the } i\text{th deep essential return is } \gamma_i, \forall i \in \{1, \ldots, s\}\}.$$

Remark 5.1. Observe that the upper bound $2n/\Theta$ for the number of deep essential returns up to time n derives from the fact that each deep essential return originates a bound period of length at least $\frac{1}{2}\Theta$ (see §3.2). Since during the bound periods there cannot be any essential return, the number of deep essential returns occurring in a period of length n is at most $n/(\frac{1}{2}\Theta)$.

PROPOSITION 5.2. *Given the integers $0 \leq s \leq 2n/\Theta$ and $s \leq v \leq n$, consider s integers $\gamma_1, \ldots, \gamma_s$, each greater than or equal to Θ. If Θ is large enough, then*

$$\lambda(A^{v,s}_{\gamma_1,\ldots,\gamma_s}(n)) \leq \binom{v}{s} \exp\left\{-(1-6\beta)\sum_{i=1}^{s}\gamma_i\right\}.$$

Proof. Fix $n \in \mathbb{N}$ and take $\omega_0 \in \mathcal{P}_0$. Note that the functions v_n, s_n and $\mathfrak{S}_n$ are constant on each $\omega \in \mathcal{P}_n$. Let $\omega \in \omega_0 \cap \mathcal{P}_n$ be such that $v_n(\omega) = v$. Then, there is a sequence $1 \leq t_1 \leq \cdots \leq t_v \leq n$ of essential return situations. Let ω_i denote the element of the partition $\mathcal{P}_{t_i}$ that contains ω. We have $\omega_0 \supset \omega_1 \supset \cdots \supset \omega_v = \omega$. For each $j \in \{0, \ldots, v\}$ we define the set

$$Q_j = \bigcup_{\omega \in \mathcal{P}_n \cap \omega_0} \omega_j,$$

and its partition

$$\mathcal{Q}_j = \{\omega_j : \omega \in \mathcal{P}_n \cap \omega_0\}.$$

Let $\omega \in \mathcal{P}_n$ be such that $\mathfrak{S}_n(\omega) = s$. Then, we may consider $1 \leq r_1 \leq \cdots \leq r_s \leq v$ with r_i indicating that the ith deep essential return occurs in the r_ith essential return situation. Now, set $V(0) = Q_0 = \omega_0$. Fix s integers $1 \leq r_1 \leq \cdots \leq r_s \leq v$. Next, for each $j \leq v$ we define recursively the sets $V(j)$. Although the set $V(v)$ will depend on the fixed integers $1 \leq r_1 \leq \cdots \leq r_s \leq v$, we do not indicate this so that the notation is not overloaded. Suppose that $V(j-1)$ is already defined and $r_{i-1} < j < r_i$. Then, we set

$$V(j) = \bigcup_{\omega \in \mathcal{Q}_j} \omega \cap f_a^{-t_j}(I - U_\Theta) \cap V(j-1).$$

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If $j = r_i$ then we define

$$V(j) = \bigcup_{\omega \in \mathcal{Q}_j} \omega \cap f_a^{-t_j}(I_{\gamma_i} \cup I_{-\gamma_i}) \cap V(j-1).$$

Observe that for every $j \in \{1, \ldots, v\}$ we have $|V(j)|/|V(j-1)| \leq 1$. Therefore, we concentrate on finding a better estimate for $|V(r_i)|/|V(r_i-1)|$. Consider that $\omega_{r_i} \in \mathcal{Q}_{r_i} \cap V(r_i)$ and let $\omega_{r_i-1} \in \mathcal{Q}_{r_i-1} \cap V(r_i-1)$ contain ω_{r_i}. We have to consider two situations depending on whether t_{r_i-1} is an escaping situation or an essential return.

Let us suppose first that t_{r_i-1} is an essential return with return depth η. Then,

$$\begin{aligned}
\frac{|\omega_{r_i}|}{|\omega_{r_i-1}|} &\leq \frac{|\omega_{r_i}|}{|\widehat{\omega}_{r_i-1}|} \quad \text{where } \widehat{\omega}_{r_i-1} = \omega_{r_i-1} \cap f_a^{-t_{r_i}}(U_1) \\
&\leq C \frac{|f_a^{t_{r_i}}(\omega_{r_i})|}{|f_a^{t_{r_i}}(\widehat{\omega}_{r_i-1})|} \quad \text{by (3.3)} \\
&\leq C \frac{2e^{-\gamma_i}}{e^{-5\beta\eta}} \quad \text{by (3.4).}
\end{aligned}$$

Note that when $r_{i-1} = r_i - 1$ then $\eta = \gamma_{i-1}$. If, on the other hand, $r_{i-1} < r_i - 1$ then t_{r_i-1} is an essential return with depth $\eta < \Theta \leq \gamma_{i-1}$. Thus, in both situations, we have

$$\frac{|\omega_{r_i}|}{|\omega_{r_i-1}|} \leq 2C \frac{e^{-\gamma_i}}{e^{-5\beta\gamma_{i-1}}}.$$

When t_{r_i-1} is an escape situation, instead of using (3.4), we can use (3.5) and obtain

$$\frac{|\omega_{r_i}|}{|\omega_{r_i-1}|} \leq 2C \frac{e^{-\gamma_i}}{e^{-\beta\Delta}} \leq 2C \frac{e^{-\gamma_i}}{e^{-5\beta\gamma_{i-1}}}.$$

Observe also that if $\widehat{\omega}_{r_i-1} \neq \omega_{r_i-1}$ then, because we are assuming that $\omega_{r_i} \neq \emptyset$, we have $|f_a^{t_{r_i}}(\widehat{\omega}_{r_i-1})| \geq e^{-1} - e^{-\Theta} \geq e^{-5\beta\gamma_{i-1}}$, for large Θ.

At this point we may write

$$\begin{aligned}
|V(r_i)| &= \sum_{\omega_{r_i} \in \mathcal{Q}_{r_i} \cap V(r_i)} \frac{|\omega_{r_i}|}{|\omega_{r_i-1}|} |\omega_{r_i-1}| \\
&\leq 2Ce^{-\gamma_i} e^{5\beta\gamma_{i-1}} \sum_{\omega_{r_i} \in \mathcal{Q}_{r_i} \cap V(r_i)} |\omega_{r_i-1}| \\
&\leq 2Ce^{-\gamma_i} e^{5\beta\gamma_{i-1}} |V(r_i-1)|.
\end{aligned}$$

This yields

$$|V(v)| \leq (2C)^s \exp\left\{-(1-5\beta)\sum_{i=1}^{s} \gamma_i\right\} e^{5\beta\gamma_0} |V(0)|,$$

where γ_0 is given by the interval $\omega_0 \in \mathcal{P}_0$. If $\omega_0 = I_{(\eta_0, k_0)}$ with $|\eta_0| \geq \Delta$ and $1 \leq k_0 \leq \eta_0^2$, then $\gamma_0 = |\eta_0|$. If $\omega_0 = (\delta, 1]$ or $\omega_0 = [-1, -\delta)$, then we can take $\gamma_0 = 0$.

Now we have to take into account the number of possibilities of having the occurrence of the event $V(v)$ implying the occurrence of the event $A^{v,s}_{\gamma_1,\ldots,\gamma_s}(n)$. The number of possible

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configurations related with the different values that the integers $r_1, \dots, r_s$ can take is $\binom{v}{s}$. Hence, it follows that

$$\begin{aligned}
\lambda(A^{v,s}_{\gamma_1,\dots,\gamma_s}(n)) &\le (2C)^s \binom{v}{s} \exp\left\{-(1-5\beta)\sum_{i=1}^{s}\gamma_i\right\} \sum_{\omega_o\in\mathcal{P}_0} e^{5\beta|\gamma_0|}|\omega_0| \\
&\le (2C)^s \binom{v}{s} \exp\left\{-(1-5\beta)\sum_{i=1}^{s}\gamma_i\right\}\left(2(1-\delta)+\sum_{|\eta_0|\ge\Delta} e^{5\beta\eta_0}e^{-|\eta_0|}\right) \\
&\le 3(2C)^s \binom{v}{s} \exp\left\{-(1-5\beta)\sum_{i=1}^{s}\gamma_i\right\} \quad \text{for } \Delta \text{ large enough} \\
&\le \binom{v}{s} \exp\left\{-(1-6\beta)\sum_{i=1}^{s}\gamma_i\right\}.
\end{aligned}$$

The last inequality results from the fact that $s\Theta \le \sum_{i=1}^{s}\gamma_i$ and the freedom to choose a sufficiently large Θ. □

Given the integers $0 \le s \le 2n/\Theta$, $s \le v \le n$ and the integers γ_0, γ_1, both greater than or equal to Θ, we consider the event

$$B^{v,s}_{\gamma_0,\gamma_1}(n) = \{x \in I_{\gamma_0} : v_n(x) = v,\ \mathfrak{S}_n(x) = s \ \text{ and } n \text{ is a free deep return with depth } \gamma_1\}.$$

COROLLARY 5.3. *Consider the integers $0 \le s \le 2n/\Theta$, $s \le v \le n$ and γ_0, $\gamma_1 \ge \Theta$. If Θ is large enough, then*

$$\lambda(B^{v,s}_{\gamma_0,\gamma_1}(n)) \le \binom{v}{s} \exp\{-(1-6\beta)(\gamma_0+\gamma_1)\}.$$

The proof of this statement follows easily from Proposition 5.2, by observing that, although n may be an inessential deep return time (instead of an essential deep return), the estimates still prevail and for $\Theta > \Delta$ large enough we have $\sum_{\gamma\ge\Theta} e^{-(1-6\beta)\gamma} \le 1$.

6. *The condition $D'(u_n)$*

Assume that $X_0, X_1, \dots$ is the stationary stochastic process defined in (1.1) with common d.f. G_a. For $z \in [-1, 1]$ the event $\{X_j(z) > u_n\}$ corresponds to the set $f_a^{-j}((u_n, 1])$. If n is sufficiently large, then $f_a^{-1}(u_n, 1] = (-\sqrt{(1-u_n)/a}, \sqrt{(1-u_n)/a}) \subset U_\Delta$. We may define

$$\Theta = \Theta(n) = \left[-\frac{1}{2}\log\frac{1-u_n}{a}\right]. \tag{6.1}$$

This way, if an exceedance occurs at time j then a deep return with depth over the threshold Θ must have happened at time $j-1$, i.e. if $X_j(z) > u_n$ then $X_{j-1}(z) = f_a^{j-1}(z) \in U_\Theta$.

Remember that the sequence u_n is such that $n(1-G_a(u_n)) \to \tau$, as $n \to \infty$, which we rewrite as $1 - G_a(u_n) \asymp 1/n$. Then, by (4.1), we get $u_n \asymp 1 - 1/n^2$, which according to (6.1) leads to

$$\Theta \asymp \log n, \tag{6.2}$$

meaning that $\Theta/\log n \to c$, for some $c > 0$, as $n \to \infty$.

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Observe that we are dealing with very small perturbations of f_2 for which $f_2^j(0) = -1$ for every $j \geq 2$. Thus, one expects that after a deep return to the critical region (a tight vicinity of zero) it should take a considerable amount of time before another deep return should occur. Since exceedances are related with the occurrence of deep returns then one may have a fair amount of belief that condition (2.2) holds for the sequence $X_0, X_1, \ldots$.

Remark 6.1. If the sequence $X_0, X_1, \ldots$ was independent, then (2.2) would follow easily since

$$\begin{aligned} n \sum_{j=1}^{[n/k]} P\{X_0 > u_n \text{ and } X_j > u_n\} &= n \sum_{j=1}^{[n/k]} P\{X_0 > u_n\} P\{X_j > u_n\} \\ &= n \sum_{j=1}^{[n/k]} (1 - G_a(u_n))^2 \\ &\leq \frac{n^2}{k} (1 - G_a(u_n))^2 \xrightarrow[n\to\infty]{} \frac{\tau^2}{k} \xrightarrow[k\to\infty]{} 0. \end{aligned}$$

Let us give some insight into the argument we use to prove that (2.2) holds for $X_0, X_1, \ldots$.

(1) We use the exponential decay of correlations (see (3.6)) to compute a turning instant $T = T(n)$ such that the dependence between X_0 and X_j with $j > T$ is negligible. This suggests the splitting of the time interval $\{1, \ldots, [n/k]\}$ into $\{1, \ldots, T\}$ and $\{T+1, \ldots, [n/k]\}$, when n is sufficiently large.

(2) During the time interval $\{T+1, \ldots, [n/k]\}$ we use the fact that for $j > T$ the r.v. X_j is almost independent of X_0 and argue as in Remark 6.1.

(3) For $j \in \{1, \ldots, T\}$ we appeal to Corollary 5.3 to bound $P\{X_0 > u_n \text{ and } X_j > u_n\}$ and afterwards we use the fact that, for n large, $T \ll [n/k]$ to finish the proof.

Step (1). Taking $\varphi = \psi = \mathbf{1}_{(u_n,1]}$ in (3.6), we get

$$\begin{aligned} &|\mu_a\{X_0 > u_n \text{ and } X_j > u_n\} - [\mu_a\{X_0 > u_n\}]^2| \\ &\qquad = \left| \int \mathbf{1}_{(u_n,1]} \cdot \mathbf{1}_{(u_n,1]} \circ f_a^j \, d\mu_a - \left(\int \mathbf{1}_{(u_n,1]} d\mu_a \right)^2 \right| \leq C\varsigma^j, \end{aligned}$$

where we may assume that C is the same for all $n \in \mathbb{N}$, because $\|\mathbf{1}_{(u_n,1]}\|_\infty = 1$ and the total variation of $\mathbf{1}_{(u_n,1]}$ is equal to 1, for every $n \in \mathbb{N}$.

We compute $T = T(n)$ such that for every $j \geq T$ we have

$$C\varsigma^j < \frac{1}{n^3}.$$

Since $C\varsigma^j < 1/n^3 \Leftrightarrow j > (1/\log \varsigma^{-1})(3 \log n + \log C)$, we simply take, for n sufficiently large,

$$T = \frac{4}{\log \varsigma^{-1}} \log n. \tag{6.3}$$

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For fixed k and n sufficiently large, we have that $T < [n/k]$. Hence, we may write

$$n \sum_{j=1}^{[n/k]} P\{X_0 > u_n \text{ and } X_j > u_n\}$$
$$= n \sum_{j=1}^{T} P\{X_0 > u_n \text{ and } X_j > u_n\} + n \sum_{j=T+1}^{[n/k]} P\{X_0 > u_n \text{ and } X_j > u_n\}.$$

In step (2) below we deal with the second term in the sum, leaving the first term for step (3).

Step (2). Let us show that $\limsup_{n\to\infty} n \sum_{j=T+1}^{[n/k]} P\{X_0 > u_n \text{ and } X_j > u_n\} \to 0$, as $k \to \infty$. By choice of T we have

$$n \sum_{j=T+1}^{[n/k]} P\{X_0 > u_n \text{ and } X_j > u_n\} \le n\left((1 - G_a(u_n))^2 + \frac{1}{n^3}\right)[n/k]$$
$$\le \frac{n^2}{k}(1 - G_a(u_n))^2 + \frac{n^2}{kn^3}.$$

Now,

$$\frac{n^2}{k}(1 - G_a(u_n))^2 + \frac{n^2}{kn^3} \xrightarrow[n\to\infty]{} \frac{\tau^2}{k} \xrightarrow[k\to\infty]{} 0$$

and the result follows.

Step (3). We are left with the burden of controlling the term $n \sum_{j=1}^{T} P\{X_0 > u_n \text{ and } X_j > u_n\}$. We begin with the following lemma that will enable us to bound the number of exceedances occurring during the time period $\{1, \ldots, T\}$. In what follows, we always assume that n is large enough so that $\Theta > \Delta$.

LEMMA 6.2. *If a deep return occurs at time t (with depth over the threshold Θ), then the next deep return can only occur after $t + \Theta/2$.*

Proof. For every $x \in U_\Theta$, the bound period associated to x is such that $p(x) \ge \Theta/2$, by §3.2 (1). For all $j \le [\Theta/2]$ we have

$$|f_a^j(x)| \ge |f_a^j(0)| - e^{-\beta j} \overset{(BA)}{\ge} e^{-\alpha\sqrt{j}} - e^{-\beta j} \ge e^{-\alpha j}(1 - e^{(\alpha-\beta)j})$$
$$\ge e^{-\alpha j}(1 - e^{(\alpha-\beta)}) \quad \text{since } \alpha - \beta < 0$$
$$\ge e^{-\alpha\Theta/2}(1 - e^{(\alpha-\beta)}) \quad \text{since } j \le \Theta/2$$
$$\ge e^{-\alpha\Theta} \quad \text{if } n \text{ is large enough so that } 1 - e^{\alpha-\beta} \ge e^{-\alpha\Theta/2}$$
$$\ge e^{-\Theta} \quad \text{since } \alpha < 1. \qquad \square$$

As a consequence of Lemma 6.2 we have that the maximum number of exceedances up to time T is at most $2T/\Theta$.

The next lemma shows that, in the bound period following a deep return over the level Θ, there cannot occur deep bound returns before time T.

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LEMMA 6.3. *For every $a \in \mathcal{BC}$, if n is sufficiently large then for every $x \in U_\Theta$ we have that $f_a^j(x) \notin U_\Theta$ for all $j \le \min\{p(x), T\}$.*

Proof. Consider the map $h : [1, \infty) \to \mathbb{R}$ given by $h(y) = e^{-\alpha\sqrt{y}} - e^{-\beta y}$. There exists $J = J(\alpha, \beta) \in \mathbb{N}$ such that $h'(y) < 0$ for every $y \ge J$. Let $D = e^{-\alpha\sqrt{J}}$.

Having in mind that by (6.2) and (6.3) we have $\Theta = \Theta(n) \asymp \log n$ and $T \asymp \log n$, respectively, assume that n is large enough so that:

(1) $e^{-\Theta} < D/2$;

(2) by continuity of f_a, for every $x \in U_\Theta$ and all $j \le J$ we have $|f_a^j(x) - f_a^j(0)| < D/2$;

(3) $e^{-\alpha\sqrt{T}} - e^{-\beta T} > e^{-\Theta}$.

Let $x \in U_\Theta$ and consider $j \le \min\{p(x), J\}$. By assumption (2) we have $|f_a^j(x) - f_a^j(0)| < D/2$. Using (BA) and hypothesis (1) we get

$$|f_a^j(x)| \ge |f_a^j(0)| - |f_a^j(x) - f_a^j(0)| \ge D - D/2 \ge D/2 > e^{-\Theta}.$$

Now, let $x \in U_\Theta$ and consider $J < j \le \min\{p(x), T\}$. Using the definition of bound period, (BA) and condition (3) we have

$$|f_a^j(x)| \ge |f_a^j(0)| - |f_a^j(x) - f_a^j(0)| \ge e^{-\alpha\sqrt{j}} - e^{-\beta j} \ge e^{-\alpha\sqrt{T}} - e^{-\beta T} > e^{-\Theta},$$

where the third inequality derives from the fact that on $[J, \infty)$ the function h is decreasing. □

As a consequence, if there is a deep return at time t, then we cannot have bound returns during the time period $(t, t + T]$. This way, we may use Corollary 5.3 to estimate $|U_\Theta \cap f_a^{-j} U_\Theta|$, for $j \le T$.

Observe that, for n large enough, we have

$$\begin{aligned} P\{X_0 > u_n \text{ and } X_j > u_n\} &= \mu_a\{(u_n, 1] \cap f_a^{-j}(u_n, 1]\} \\ &= \mu_a\{f_a^{-1}(u_n, 1] \cap f_a^{-(j+1)}(u_n, 1]\}, \end{aligned}$$

and $f_a^{-1}(u_n, 1] \cap f_a^{-j}(f_a^{-1}(u_n, 1]) \subset U_\Theta \cap f_a^{-j} U_\Theta$. In what follows we will use 'const' to denote several positive constants independent of n.

Note that

$$U_\Theta \cap f_a^{-j} U_\Theta \subset \bigcup_{s=0}^{2j/\Theta} \bigcup_{v=s}^{j} \bigcup_{\gamma_0 \ge \Theta} \bigcup_{\gamma_1 \ge \Theta} B_{\gamma_0,\gamma_1}^{v,s}(j).$$

Hence, by Corollary 5.3, we have

$$\begin{aligned} |U_\Theta \cap f_a^{-j} U_\Theta| &\le \sum_{s=0}^{2j/\Theta} \sum_{v=s}^{j} \sum_{\gamma_0 \ge \Theta} \sum_{\gamma_1 \ge \Theta} \binom{v}{s} e^{-(1-6\beta)(\gamma_0+\gamma_1)} \\ &\le \text{const} \sum_{s=0}^{2T/\Theta} \sum_{v=s}^{T} \binom{v}{s} e^{-(1-6\beta)2\Theta} \\ &\le \text{const} \sum_{s=0}^{2T/\Theta} \sum_{v=s}^{T} \binom{T}{s} e^{-(1-6\beta)2\Theta} \le \text{const} \sum_{s=0}^{2T/\Theta} T \binom{T}{s} e^{-(1-6\beta)2\Theta}. \end{aligned}$$

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At this point, we estimate $2T/\Theta$. Recalling (6.2) and (6.3), one easily gets that there exists a constant $C_1 > 0$ such that $2T/\Theta \le C_1$, for n sufficiently large. So, to proceed with the estimation $|U_\Theta \cap f_a^{-j} U_\Theta|$, assume that n is sufficiently large so that $2T/\Theta \le C_1$ and $C_1 \ll T$. Then,

$$\begin{aligned}|U_\Theta \cap f_a^{-j} U_\Theta| &\le \text{const} \sum_{s=0}^{2T/\Theta} T\binom{T}{s} e^{-(1-6\beta)2\Theta} \le \text{const} \sum_{s=0}^{2T/\Theta} T\binom{T}{C_1} e^{-(1-6\beta)2\Theta} \\ &\le \text{const}\, \frac{2T}{\Theta} T\binom{T}{C_1} e^{-(1-6\beta)2\Theta} \le \text{const}\, T^{C_1+1} e^{-(1-6\beta)2\Theta}.\end{aligned}$$

So far we managed to obtain an estimate for $|U_\Theta \cap f_a^{-j} U_\Theta|$. Let us see how to derive one for $P\{X_0 > u_n \text{ and } X_j > u_n\} \le \mu_a\{U_\Theta \cap f_a^{-j} U_\Theta\}$. By assertion (3) in §3.6 we have

$$\begin{aligned}\mu_a\{U_\Theta \cap f_a^{-j} U_\Theta\} &= \int_{U_\Theta \cap f_a^{-j} U_\Theta} \rho_1^a(x)\, dx + \int_{U_\Theta \cap f_a^{-j} U_\Theta} \rho_2^a(x)\, dx \\ &\le \text{const}\, |U_\Theta \cap f_a^{-j} U_\Theta| + \sum_{j=1}^{\Theta^2} \int_{U_\Theta \cap f_a^{-j} U_\Theta} \frac{(1.9)^{-j}}{\sqrt{|x - f_a^j(0)|}}\, dx \\ &\quad + \sum_{j=\Theta^2}^{\infty} \int_{U_\Theta \cap f_a^{-j} U_\Theta} \frac{(1.9)^{-j}}{\sqrt{|x - f_a^j(0)|}}\, dx.\end{aligned}$$

Using (BA) we get $|f_a^j(0)| > e^{-\alpha\Theta}$, for all $j \le \Theta^2$. Thus, for all $x \in U_\Theta$ and Θ large enough, we have $\sqrt{|x - f_a^j(0)|} > \sqrt{e^{-\alpha\Theta} - e^{-\Theta}} > 1/2.e^{-\alpha\Theta/2}$, which implies that $1/\sqrt{|x - f_a^j(0)|} \le 2e^{\alpha\Theta/2} \le 2e^{\beta\Theta}$ (recall that $\beta > \alpha$). Consequently, for sufficiently large Θ,

$$\begin{aligned}\mu_a\{U_\Theta \cap f_a^{-j} U_\Theta\} &\le \text{const}\, |U_\Theta \cap f_a^{-j} U_\Theta| + \text{const}\, |U_\Theta \cap f_a^{-j} U_\Theta|\, e^{\beta\Theta} + \text{const}\, e^{\Theta^2 \log 1.9} \\ &\le \text{const}\, T^{C_1+1} e^{-(1-7\beta)2\Theta}.\end{aligned}$$

Now, since $e^{-\Theta} \le \text{const}\, (1 - G_a(u_n))$, we finally conclude that

$$\begin{aligned}n \sum_{j=1}^{T} P\{X_0 > u_n \text{ and } X_j > u_n\} &\le \text{const}\, n \sum_{j=1}^{T} T^{C_1+1} (1 - G_a(u_n))^{2(1-7\beta)} \\ &\le \text{const}\, nT^{C_1+2} (1 - G_a(u_n))^{2(1-7\beta)} \\ &\le \text{const}\, n(\log n)^{C_1+2} (1 - G_a(u_n))^{2-14\beta} \\ &\le \text{const}\, [n(1 - G_a(u_n))]^{3/2} (1 - G_a(u_n))^{1/2-14\beta},\end{aligned}$$

for sufficiently large n. The result follows because

$$\lim_{n\to\infty} [n(1 - G_a(u_n))]^{3/2} (1 - G_a(u_n))^{1/2-14\beta} = \tau^{3/2} \cdot 0 = 0.$$

7. *Simulation study*

In this section we present a small simulation study illustrating the finite sample behavior of the normalized M_n, defined in (1.2), for the Benedicks–Carleson quadratic map

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TABLE 1. Simulation results.

		$n = 1000$		$n = 10\,000$		$n = 20\,000$
x	$H(x)$	$m = 1000$	$m = 10\,000$	$m = 10\,000$	$m = 20\,000$	$m = 20\,000$
-0.001	0.9689	0.976	0.9671	0.9719	0.9677	0.9708
-0.01	0.9048	0.894	0.9079	0.9056	0.9076	0.9052
-0.1	0.7289	0.724	0.7263	0.7323	0.7303	0.7335
-0.3	0.5783	0.569	0.5773	0.5823	0.5840	0.5813
-0.5	0.4931	0.491	0.4906	0.5012	0.4984	0.4941
-0.7	0.4332	0.407	0.4272	0.4403	0.4374	0.4338
-1	0.3679	0.388	0.3631	0.3663	0.3729	0.3678
-3	0.1769	0.164	0.1731	0.1748	0.1833	0.1729
-5	0.1069	0.124	0.1024	0.1092	0.1108	0.1056
-8	0.0591	0.059	0.0510	0.0557	0.0617	0.0580
-10	0.0423	0.049	0.0350	0.0435	0.0438	0.0414
-30	0.0042	0.002	0.0031	0.0033	0.0048	0.0041
-50	0.00085	0.001	0.0007	0.0009	0.0007	0.0009

$f_2(x) = 1 - 2x^2$. We have that $P\{X_0 \le x\} = G_2(x) = 1/2 + \arcsin(x)/\pi$. According to Theorem A, the normalizing sequence is $a_n = (1 - \cos(\pi/n))^{-1}$, for each $n \in \mathbb{N}$, and the theoretical limiting distribution for $a_n(M_n - 1)$ is

$$H(x) = \begin{cases} e^{-(-x)^{1/2}}, & x \le 0, \\ 1, & x > 0. \end{cases}$$

We performed the following experiment. We picked at random (according to the d.f. G_2) a point z in the interval $[-1, 1]$, computed its orbit up to time n and calculated $M_n(z) = \max\{z, f_2(z), \ldots, f_2^{n-1}(z)\}$. We repeated the process m times to obtain a sample $\{M_n(z_1), \ldots, M_n(z_m)\}$ and approximated, for certain values of x, $P\{a_n(M_n - b_n) \le x\}$ by

$$\frac{1}{m} \sum_{i=1}^{m} \mathbf{1}_{\{a_n(M_n(z_i) - b_n) \le x\}}, \tag{7.1}$$

where

$$\mathbf{1}_{\{a_n(M_n(z_i) - b_n) \le x\}} = \begin{cases} 1 & \text{if } a_n(M_n(z_i) - b_n) \le x \\ 0 & \text{if } a_n(M_n(z_i) - b_n) > x \end{cases} \quad \text{for each } 1 \le i \le m.$$

In Table 1 we present the results obtained by realizing the above experiment, considering different values of x, n and m and comparing them with the theoretical limiting ones given by $H(x)$.

As one may verify, the results of the experiment are quite close to the asymptotic theoretical ones and there is a general tendency to get better as n increases, which is precisely the behavior we were expecting. It is also noticeable that there is an improvement

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when m increases, which is also predictable since our approximation (7.1) gets to be more accurate.

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