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CORRIGENDUM

Attitude stability control system for a hexapod bionic robot under hybrid disturbances – CORRIGENDUM

Ping Zhang, Jun Liu, Kai Cao, Yi Sun, Youzhi Xu, Andong Jiang, Xuefei Liu, Huan Shen and Aihong Ji

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This article was originally published with incorrect affiliations.

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The errors have been corrected and the online HTML and PDF versions updated.

The author apologises for the error.

Reference

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